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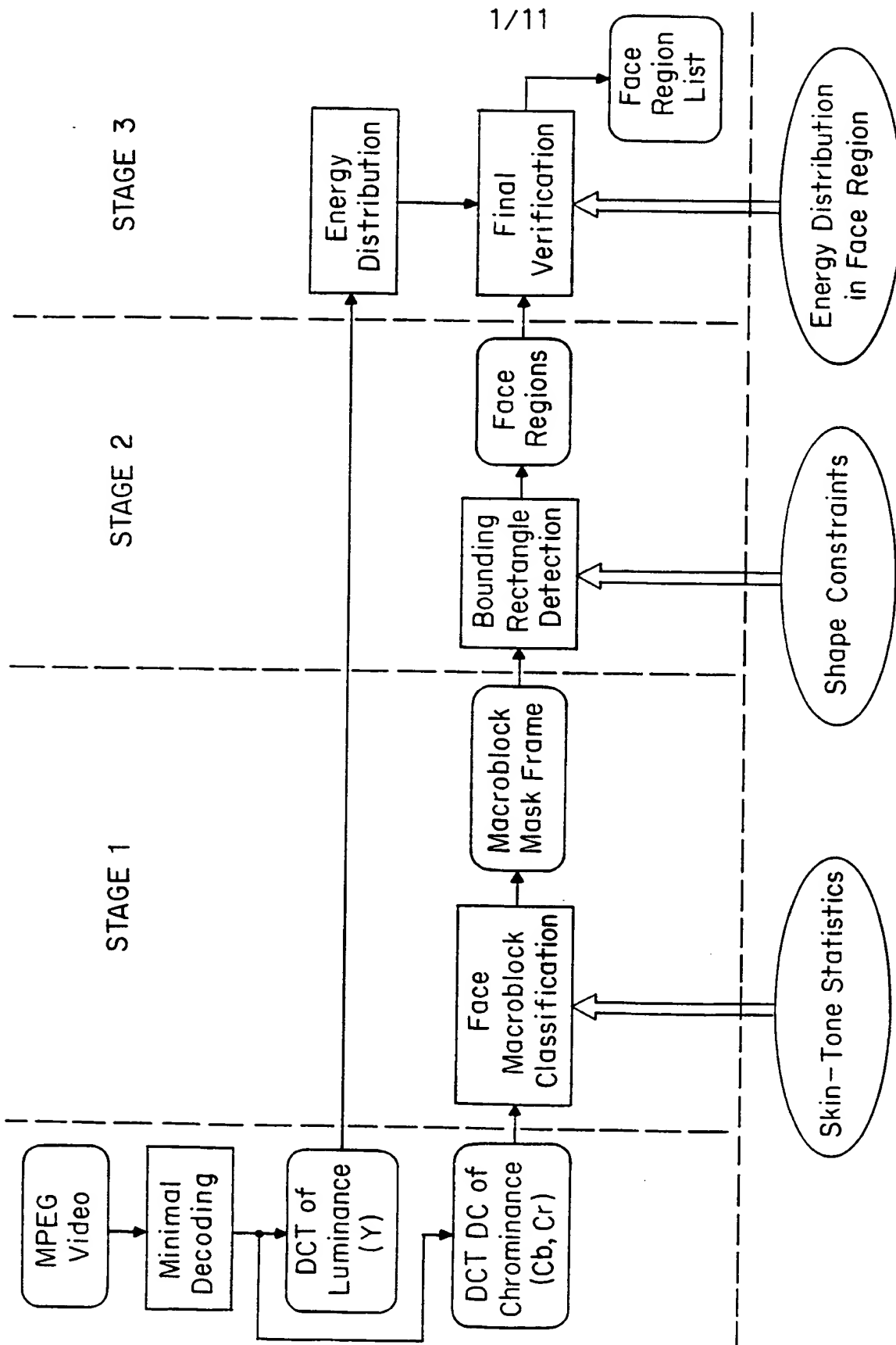


FIG. 1

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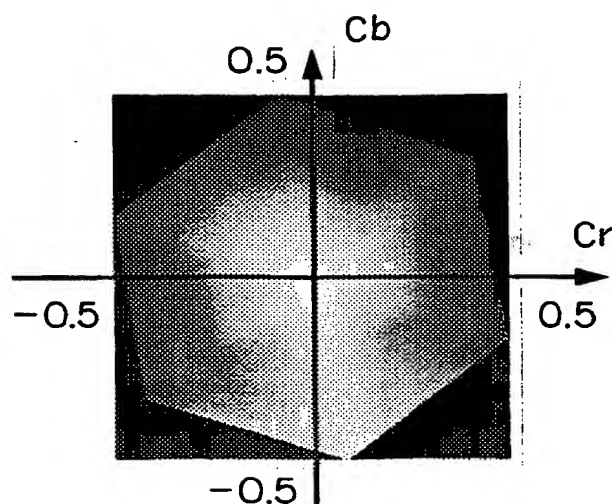


FIG. 2(a)

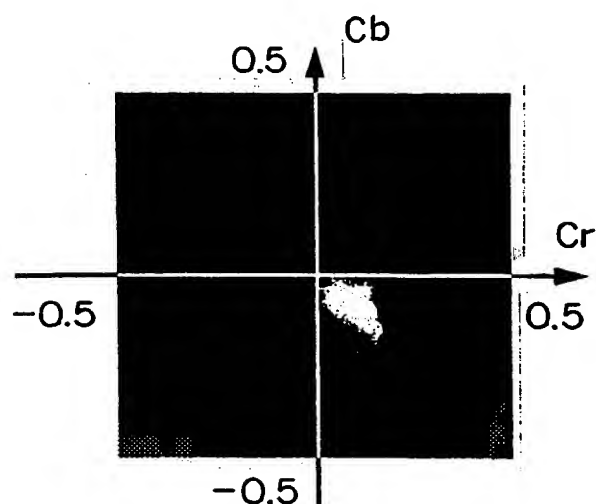


FIG. 2(b)



FIG. 3(a)



TH=20

FIG. 3(b)



TH=5

FIG. 3(c)



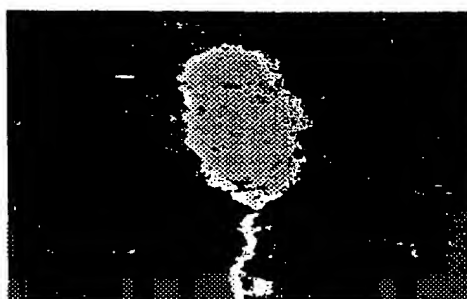
TH=2

FIG. 3(d)

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FIG. 4(a)



TH= 0.5

FIG. 4(b)



FIG. 6(a)

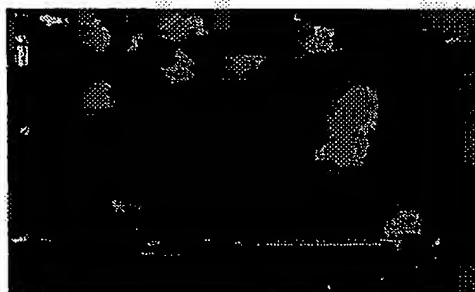


FIG. 6(b)

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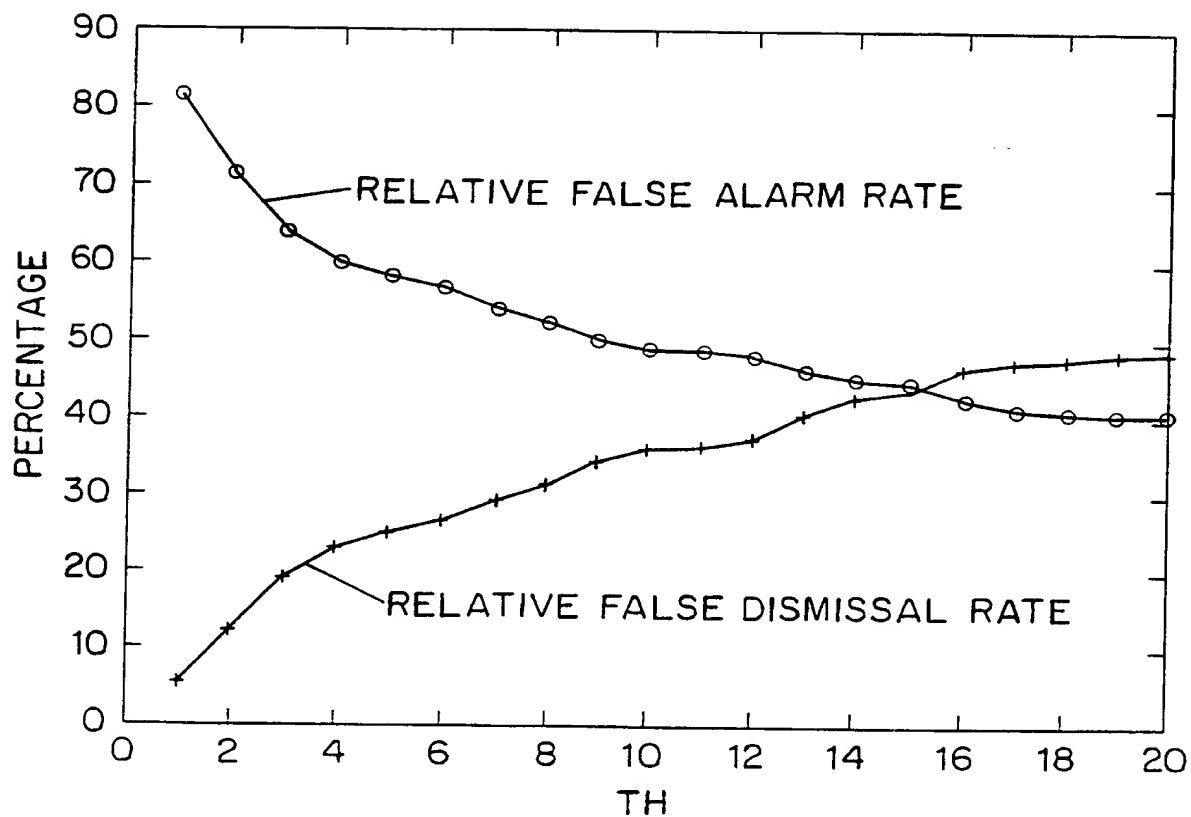


FIG. 5

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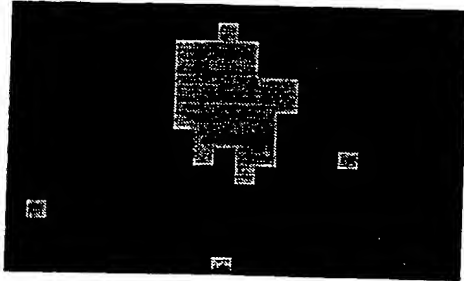


FIG. 7(a)

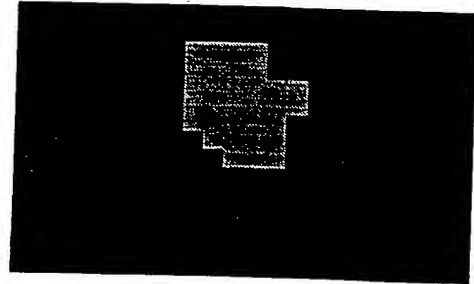


FIG. 7(b)

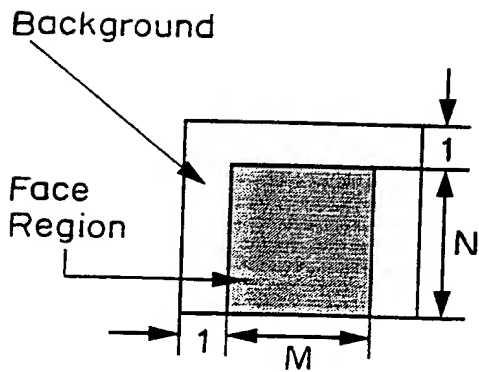


FIG. 8(a)

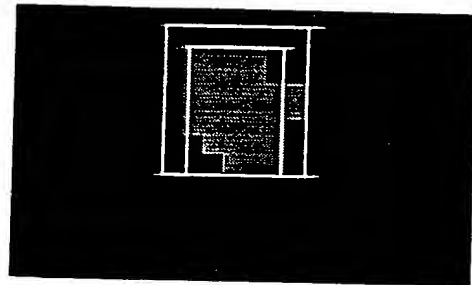


FIG. 8(b)

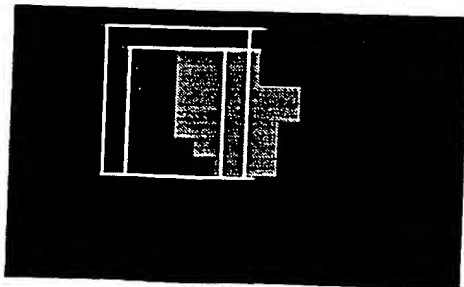


FIG. 8(c)

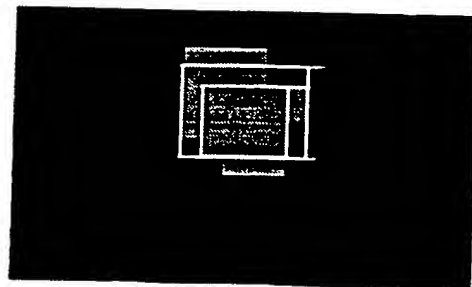


FIG. 8(d)

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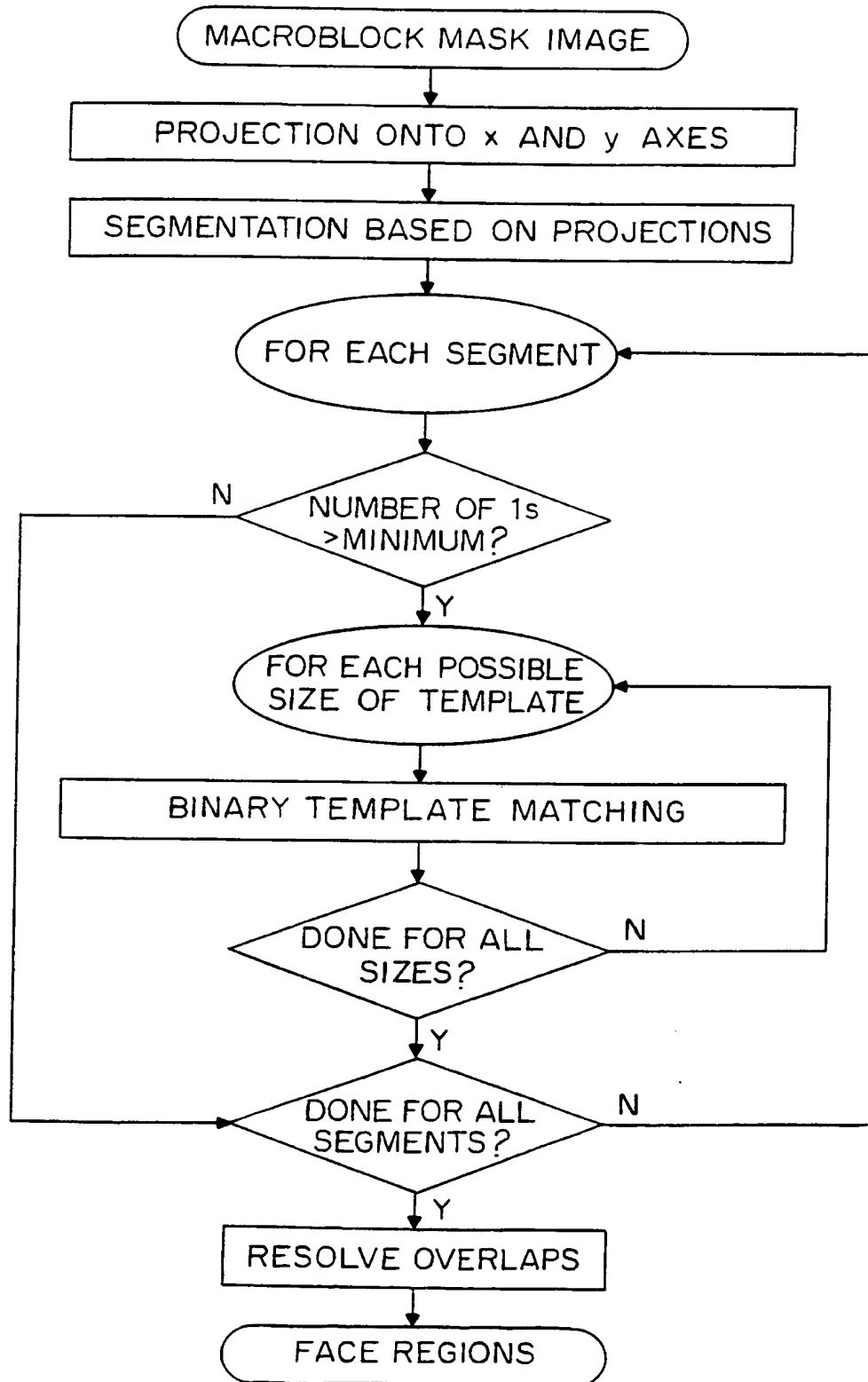


FIG. 9

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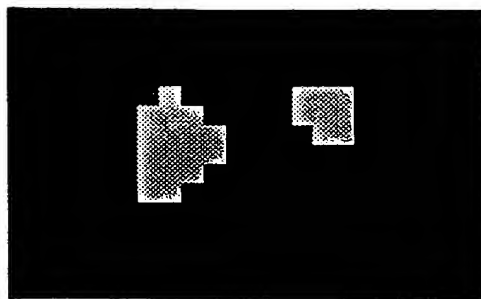


FIG. 10(a)

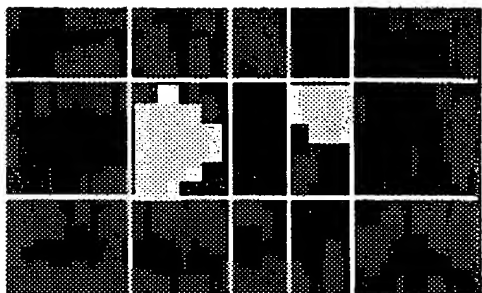


FIG. 10(b)

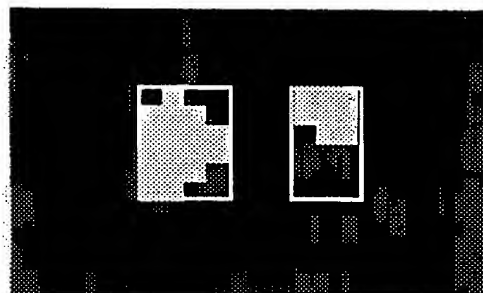


FIG. 10(c)



FIG. 11(a)

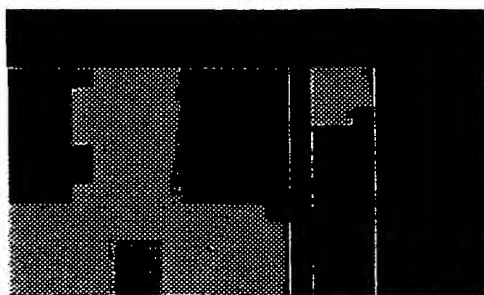


FIG. 11(b)

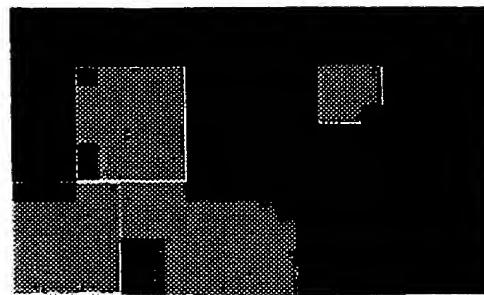


FIG. 11(c)

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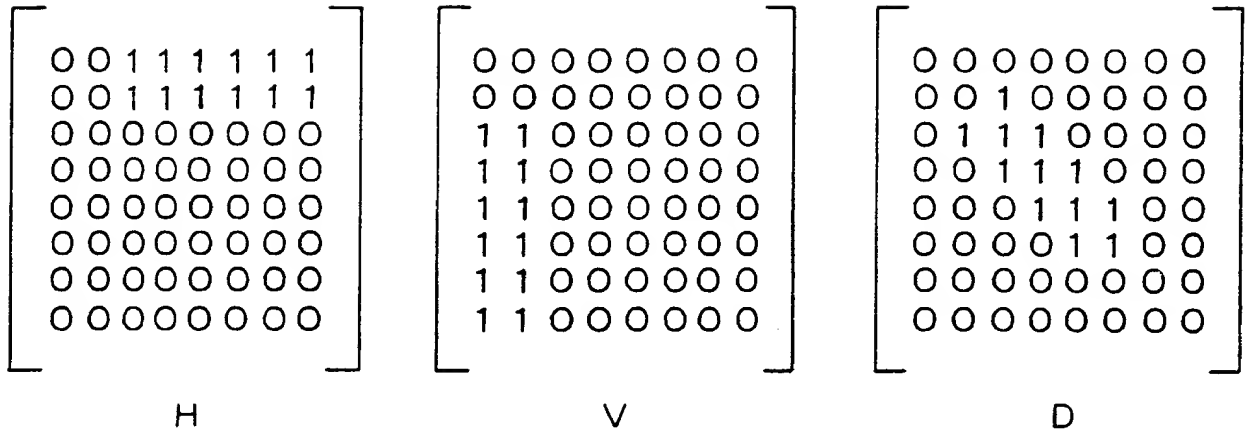


FIG. 12

MOTION VECTOR

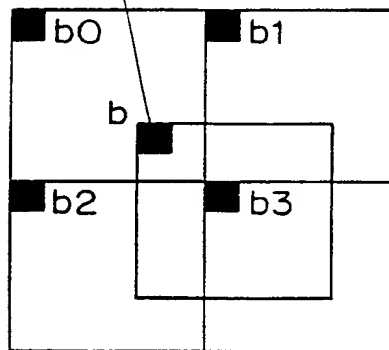


FIG. 13



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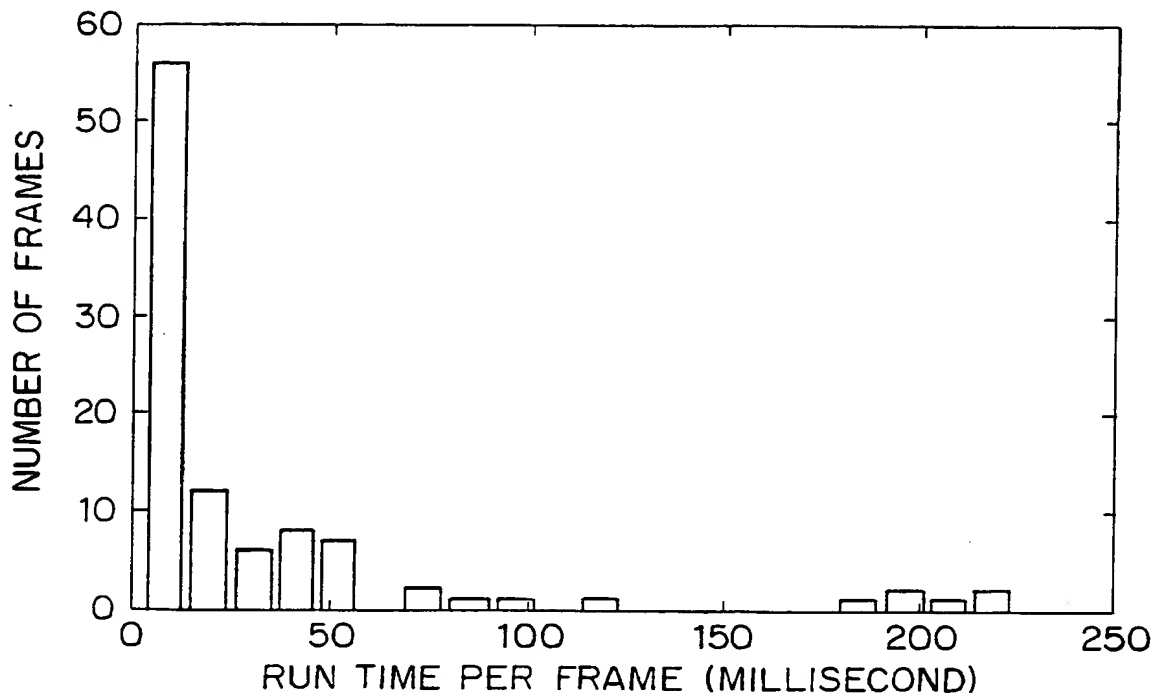


FIG. 14(a)

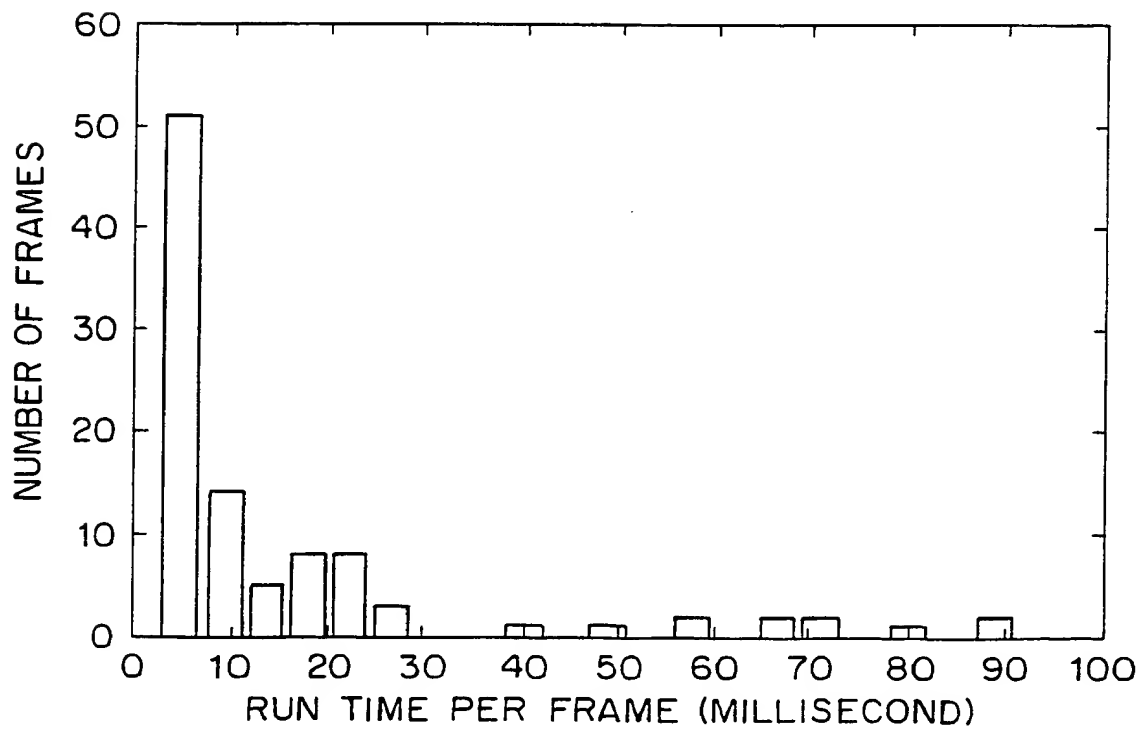


FIG. 14(b)

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FIG. 15(a)



FIG. 15(b)



FIG. 15(c)



FIG. 15(d)



FIG. 15(e)



FIG. 15(f)



FIG. 15g



FIG. 15(h)

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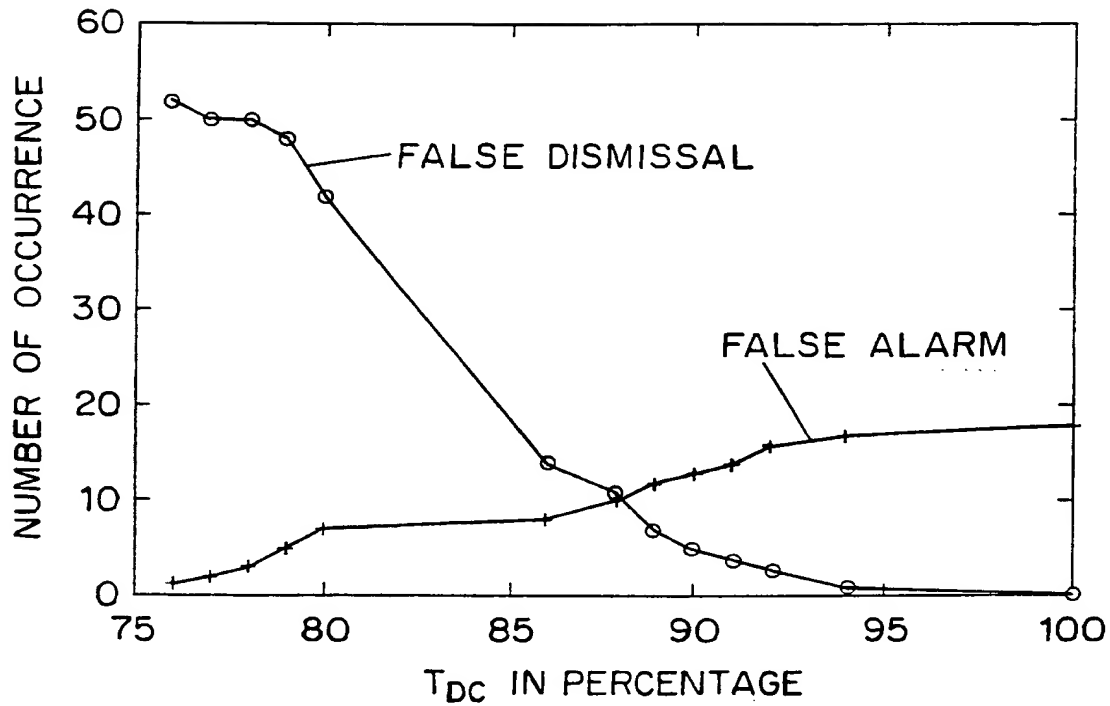


FIG. 16 (a)

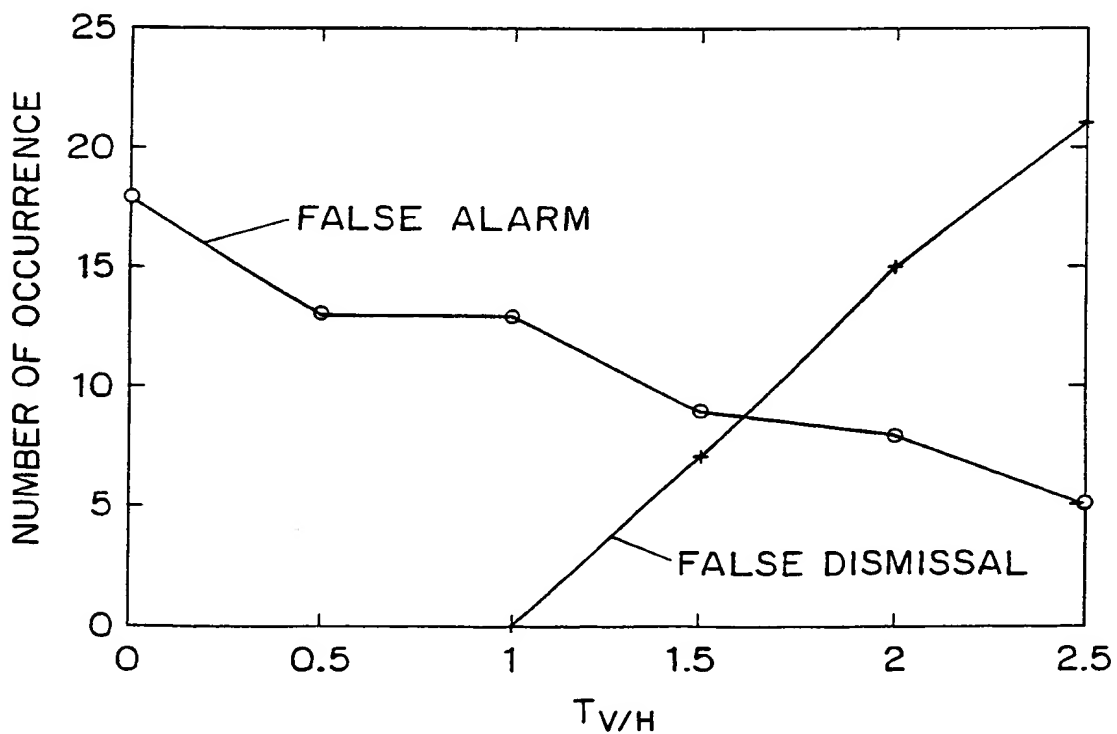


FIG. 16 (b)